

## High Performance Systems Introduction

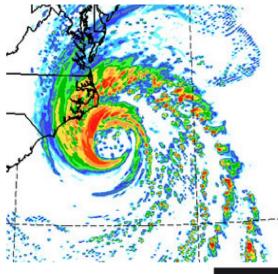
## Elisabeth Brunet CSC5001 - Septembre 2023



# Scientific Computing and simulation

- Essential for scientific and industrial innovation
- Numerous fields of application

   Meteorology, astrophysics, nanoscience, etc.
   Automotive, aeronautics, 7th art, defense, etc.
- Simulation is necessary when the problems are ...
  - I...too complex
  - 0...to massive
  - I...too expensive
  - I...too dangerous
  - <sup>I</sup>...predictive





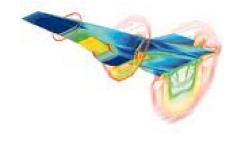
# Scientific Computing and simulation

- A lot of calculation
- Handling of huge amounts of data
- Time constraints

### Consequences

Increased computing resourcesParallelization of problems

- To go faster and faster
- but above all to deal with ever bigger problems





## High Performance Platforms

- Component capacities maximized
- Processor diversity
  - Boosted consumer architectures
  - Specialized Architectures
    - <sup>I</sup> Processors Alpha, MIPS, Cray, Power, Sparc, NEC, etc.
      - Instruction sets
      - Architectural processing flow
        - Vectorial processor
        - Processor Cell





• Processor design by IBM, Sony and Toshiba in 2005

#### Totally different architectural model

1 master PowerPC processor called PPE

<sup>1</sup> 8 SPE vectorial co-processors

<sup>II</sup> Internal EIB interconnection bus

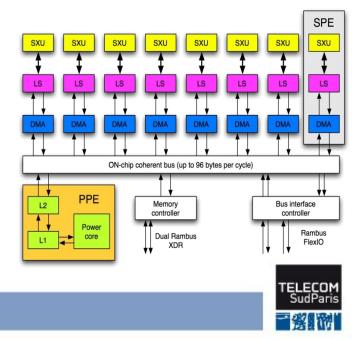
### Peak performances

<sup>1</sup> 230,4 GFLOPS in single précision

Initially designed for multimedia (PS3) and hijacked by HPC

### • Extremely difficult to program

<sup>1</sup> Abandoned in 2009



# **副多聞 High Performance Platforms**

Component capacities maximized

### • Processor diversity

- Boosted consumer architectures
- Specialized Architectures
- Co-processors
  - I FPGA : programmable logic circuit
  - **GPU**: Graphics Processing Unit





### 1 GPU = hundreds of limited cores

No dynamic memory allocationNo stack, so no recursivity

### • Design for 3D image synthesis

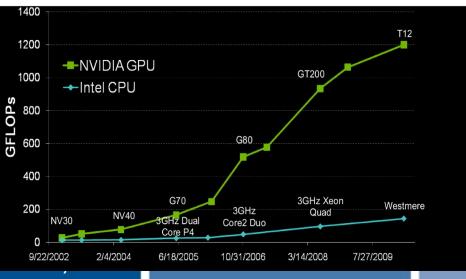
3D API : OpenGL, DirectX

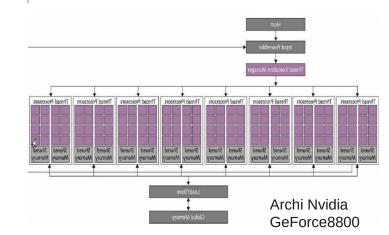
### Then parallel computing focus

<sup>I</sup> Nvidia : Architecture Tesla(2006), Fermi(2009) / API CUDA

<sup>I</sup> AMD : Archi RadeonHD / API ATI Stream SDK

<sup>I</sup> API unifiée GPU+CPU : OpenCL (2008)





### Vectorial computation offloading

- <sup>I</sup> Suitable to massively parallel compute
- Data transfert
- Kernel computation
- Result transfert
- Slow CPU/GPU communication



# **副選択** High Performance Platforms

Component capacities maximized

### • Processor diversity

- Boosted consumer architectures
- Specialized Architectures
- Co-processors
- Massive aggregation of resources
  - <sup>I</sup> High performance networks InfiniBand, Myrinet, 10G-Ethernet, etc.
  - <sup>I</sup> Topologies : supercomputer, cluster, grid



# **全部的**Computing resources in HPC

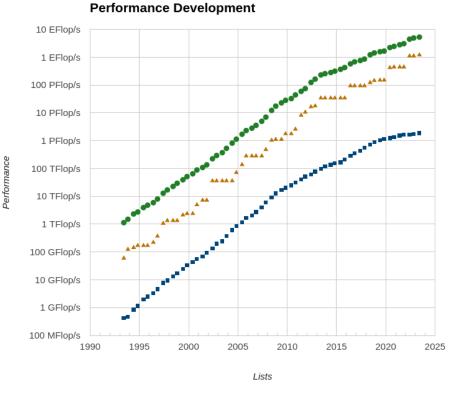
- Hybrid architectures
- High capabiliy components
- Ever increasing computing power
  - Petascale (10^15 floating point operations per second), even exascale

Top500 ranking

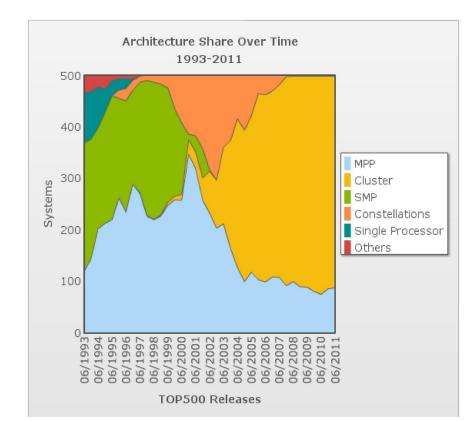




Bi-annual ranking of the 500 most powerful machines in the world



● Sum ▲ #1 ■ #500







1 Frontier - HPE Cray EX235a, AMD EPYC 64C 2GHz, AMD Instinct MI250X – Oak Ridge (USA)

#cores = 8,699,904 Rmax = 1,194.00 Rpeak=1,679.82 Power=22,703

- 2 Fugaku A64FX48C 2.2GHz, Tofu Interconnect Fujitsu RIKEN Center of Computational Science (Japan)
   #cores = 7,630,848 Rmax = 442.01 Rpeak=537.21 Power=29,899 → #1 in 2020
- 3 Lumi HPE Cray EX235a, AMD EPYC 64C 2GHz, AMD Instinct MI250X EuroHPC CSC (Finland)

#cores = 2,220,288 Rmax = 309.10 Rpeak=428.70 Power=6,016

- 4 Leonardo –BullSequana XH2000, Xeon Platinum 2.6GHz, NVIDIA A100 64GB, Infiniband– EuroHPC CINECA (Italy) #cores = 1,824,768 Rmax = 238.70 Rpeak=304.47 Power=7,404
- **5** Summit IBM POWER9, NVIDIA Volta GV100 Oak Ridge National Lab (USA)  $\rightarrow$  #2 in 2020 # cores=2,414,592 Rmax=148,600 RPeak=200,794 Power=10,096

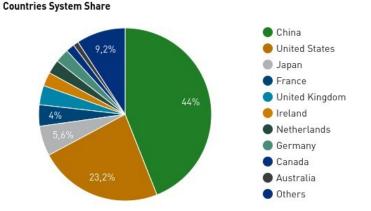




#### • 12. Adastra - HPE Cray EX235a, AMD Optimized EPYC 64C 2GHz - GENCI-CINES

#cores=319,072 Rmax=46.10 Rpeak=61.61 Power=921

- 22. CEA HF Bull Sequana X1000 Xeon Phi 7250 CEA #cores=810,240 Rmax=23.24 Rpeak=31.76 Power=4,959
- **39. PANGEA III** IBM POWER9, NVIDIA Volta GV100 Total Exploration Production
  - #cores=291 024 Rmax=17860 Rpeak=25025 Power=1367





## **警察部 Green 500 in 2020**

#### Best performance/energy consumption ratio

Rank	TOP500 Rank	System	Cores	Rmax (PFlop/s)	Power (kW)	Energy Efficiency (GFlops/watts)
1	255	Henri - ThinkSystem SR670 V2, Intel Xeon Platinum 8362 32C 2.8GHz, NVIDIA H100 80GB PCIe, Infiniband HDR, Lenovo Flatiron Institute United States	8,288	2.88	44	65.396
2	34	Frontier TDS - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Slingshot-11, HPE D0E/SC/Oak Ridge National Laboratory United States	120,832	19.20	309	62.684
3	12	Adastra - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Slingshot-11, HPE Grand Equipement National de Calcul Intensif - Centre Informatique National de l'Enseignement Suprieur (GENCI- CINES) France	319,072	46.10	921	58.021
4	17	Setonix – GPU - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Slingshot-11, HPE Pawsey Supercomputing Centre, Kensington, Western Australia Australia	181,248	27.16	477	56.983
5	77	Dardel GPU - HPE Cray EX235a, AMD Optimized 3rd Generation EPYC 64C 2GHz, AMD Instinct MI250X, Slingshot-11, HPE	52,864	8.26	146	56.491

- Most of them are accelerator-based
- Trend of aggregating many low-power processors tops the Green500



## Critical points of HPC applications

#### In terms of implementation

- Classic problems exacerbated
- Use of material resources
- Data distribution
- Dissemination of résultats

<sup>I</sup> Collective operations (*alltoall*, *broadcast*, reduction, etc.)

• Problems related to the size of the platforms

<sup>I</sup> Fault tolerance, etc.

#### In terms of efficiency

- Data locality
- Data granularity
- Load balancing



# **多聞 Support for HPC applications**

- Hardware abstraction interfaces
  - <sup>I</sup> Examples : OpenCL, PVM, MPI, etc.
  - <sup>I</sup> For software portability





### Runtimes

<sup>I</sup> Multiprocessor architectures

<sup>I</sup> Thread scheduling

<sup>I</sup> Data placement

Distributed architecturess

Data distribution

Data transfert

- I MPI, RPC, DSM , etc
- <sup>I</sup> Heterogeneous architectures

Load balancing

<sup>I</sup> StarSs, Intel Ct, StarPU, etc.

For performance portability !



## **多数** Support for HPC applications

- Libraries for classical problem solving
  - □ FFT, linear algebra (BLAS, etc.), etc.

#### • Tools

<sup>I</sup> Performance Analysis (Easytrace, Vampir, Scalasca, etc.)

<sup>II</sup> Bugs detection (Valgrind, gdb, etc.)

<sup>I</sup> Fault tolerance

0

Middlewares

<sup>I</sup> Code couplage





#### • Performance dependent on several factors

- <sup>1</sup> Fraction of the parallelizable application
- <sup>1</sup> Quality of scheduling on computing resources
- <sup>I</sup> Additional cost introduced by the parallel version
- **Speedup :** measures the acceleration between parallel and sequential versions
  - <sup>I</sup> Sp = Tseq /Tp , where
  - Sp = speedup on P procs
  - Tp = execution time on P processors
  - Tseq = execution time on 1 processor
  - <sup> $\Box$ </sup> Aiming at Sp = P
- Amdahl law : acceleration bound as a function of parallelization quality
  - R = 1 / ((1-S)+S/P), where
  - S = parallelized code ratio, P = #processors
  - <sup> $\Box$ </sup> Speedup is bounded by 1/S > addition of processors can be unnecessary

