Processes, threads and synchronizations

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Definition of a process

- A process is a **running instance** of a program
  - Allow the execution of different programs in parallel (e.g., *fortnite* and *chrome*)
  - Allow the execution of the same program multiple times (e.g., two instances of *emacs* for two different users)

- The operating system is in charge of
  - Managing the **life cycle** of the processes (start, stop)
  - Allowing processes to **communicate** (signals, pipes, sockets…)
  - (Regularly) **running** the processes on the processors
  - **Isolating** the processes (no shared memory by default)

- A process is roughly a virtualization of a complete machine
During execution, when it starts a function, the process creates a call frame

- Contains
  - the arguments of the functions
  - its local variables
  - a link to the caller
- Frees the call frame at the end of the call

```c
int add(int x, int y) {
    int z = x + y;
    return z;
}
int main(int argc, char** argv) {
    printf("%d\n", add(1, 2));
}
```
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```
From the call frame to the thread

- During execution, when it starts a function, the process creates a call frame
  - Contains
    - the arguments of the functions
    - its local variables
    - a link to the caller
  - Frees the call frame at the end of the call

- A thread is an execution context executable by a CPU
  - A stack of call frames (e.g., main calls add)
  - The next instruction to be executed (e.g., the return z)

- An operating system schedules the threads on the CPUs
Processes and threads

- A process contains
  - A memory (data, code, heap)
  - One or more threads (each with its stack and its next instruction)

- A process always starts with a single thread

- A process may create more threads to increase parallelism
  - The operating system can then schedule the multiple threads on the multiple CPUs in parallel

- A process dies when its last thread terminates
Thread identification

- Type that can hold a thread identifier: `pthread_t`
- Identifier of the running thread: `pthread_t pthread_self()`
Thread creation

int pthread_create(pthread_t* tid, pthread_attr_t* attr, void* (*start_routine)(void*), void* arg)

- Create and start a new thread
- The new thread starts in the function start_routine
- The start_routine function receives the argument arg
- pthread_create fills *tid with the identifier of the new thread
- pthread_attr_t gives attribute (scheduling, stack pointer...)

void* f(void* arg) { printf("f is running\n"); return NULL; }

int main(int argc, char** argv) {
    pthread_t tid;
    pthread_create(&tid, NULL, f, NULL);
    printf("main is running in parallel with f\n");
}
Thread termination

- After an explicit call to `pthread_exit(void* retval)`
- At the end of the `start_routine`
- The system also terminates all the threads of a process when:
  - The main function returns
  - One of the threads of the process calls `exit`
Waiting the termination of a thread

```c
int pthread_join(pthread_t thread, void** pretval);

void* f(void* arg) {
    printf("f is running\n");
    return (void*)0x42;
}

int main(int argc, char** argv) {
    pthread_t tid;
    void* retval;
    pthread_create(&tid, NULL, f, NULL);
    printf("main is running in parallel with f\n");
    pthread_join(tid, &retval);
    printf("f terminated with retval %p\n", retval);
}
```
Detached mode

By default, a thread is in the **joinable mode**
- When the thread dies, the system keeps its return value, which consumes system resources
- Another thread can use `pthread_join` to retrieve this value

In **detached mode**
- The system immediately frees all the system resources used by a thread when it exits
- It is impossible to retrieve its return value

You can change the mode of a thread to detached
- Through a call to `pthread_detach(pthread_t tid)`
- By using the `pthread_attr_t in pthread_create`
Shared variables and inconsistencies

The threads of a process share the same memory
• When a thread modifies a variable, the other threads see the modification
• Concurrent accesses may lead to inconsistencies

\[
\text{int balance} = 1000;
\]

**Thread 1**

a. void credit() {

b. int tmp = balance;

c. tmp = tmp + 100;

d. balance = tmp;

e. }

**Thread 2**

f. void debit() {

g. int tmp = balance;

h. tmp = tmp - 1;

i. balance = tmp;

j. }

Possible schedule: fg abcde hij => the credit of 100 is lost!
Principle to avoid inconsistencies

- Prevent two sections of code that access the same shared variables to execute at the same time
  - We say that the sequences of instructions are in mutual exclusions

Definition: a critical section is a section of code in mutual exclusion
- Critical sections execute entirely one after the other
- We say that a critical section executes atomically

A critical section is often in mutual exclusion with itself
Mutex: a lock in mutual exclusion
- Two possible states: busy or free
- At each time, only one thread can own (have marked as busy) the mutex

A mutex provides two operations
- Lock acquisition: waits if the lock is busy and then changes its state from free to busy
- Lock release: marks the lock as free

The two operations seem to execute atomically
Implementation of mutual exclusion

Implementation:
• `pthread_mutex_lock`: acquire a mutex
• `pthread_mutex_unlock`: release a mutex

```
int balance = 1000;
pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
```

Thread 1
```c
void credit() {
    pthread_mutex_lock(&m);
    int tmp = balance;
    tmp = tmp + 100;
    balance = tmp;
    pthread_mutex_unlock(&m);
}
```

Thread 2
```c
void debit() {
    pthread_mutex_lock(&m);
    int tmp = balance;
    tmp = tmp - 1;
    balance = tmp;
    pthread_mutex_unlock(&m);
}
```
Monitor

Allows a thread to wait for a certain condition to become true
- Built with a mutex and a variable condition

```c
char* msg = NULL;
pthread_mutex_t m = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t c = PTHREAD_COND_INITIALIZER;
```

Thread 1

```c
void send() {
    pthread_mutex_lock(&m);
    msg = "Hello!";
    pthread_cond_signal(&c);
    pthread_mutex_unlock(&m);
}
```

Thread 2

```c
void recv() {
    pthread_mutex_lock(&m);
    while(msg == NULL) {
        pthread_cond_wait(&c, &m);
    }
    printf("Message: %s\n", msg);
    pthread_mutex_unlock(&m);
}
```
Monitor

- Allow a thread to wait for a certain condition to become true
  - Built with a mutex and a variable condition

Interface

- Unlock mutex and sleep on cond
  
  ```c
  pthread_cond_wait(&cond, &mutex)
  ```

- Wake up one thread that sleeps on cond
  
  ```c
  pthread_cond_signal(&cond)
  ```

- Wake up all the threads that sleep on cond
  
  ```c
  pthread_cond_broadcast(&cond)
  ```
To take away

Thread life cycle

- `pthread_create`: create a thread
- `pthread_self`: return the thread identifier
- `pthread_exit`: quit a thread
- `pthread_join`: wait for the termination of a thread

Synchronization

- `pthread_mutex_lock`: take a lock
- `pthread_mutex_unlock`: release a lock
- `pthread_cond_wait`: wait on a condition variable
- `pthread_cond_signal`: wake up a thread that waits on a condition variable
- `pthread_cond_broadcast`: wake up all the threads that wait on a condition variable