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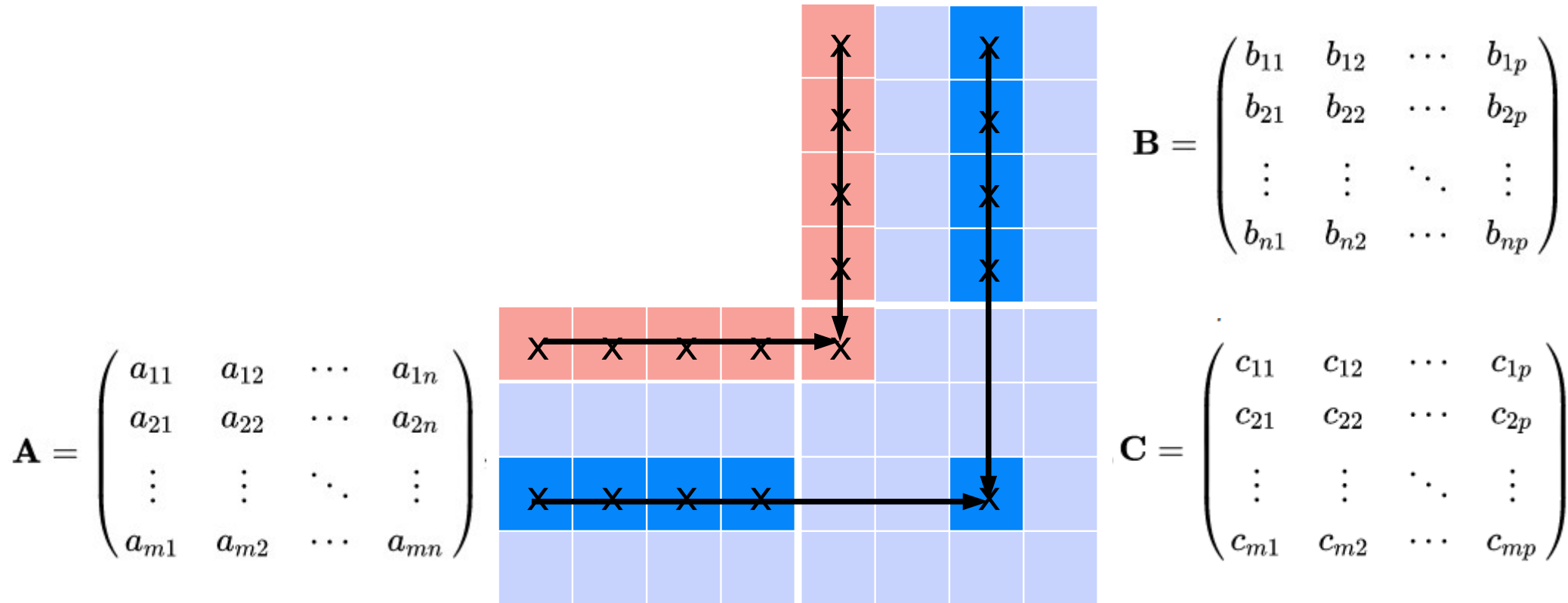
Optimized Matrix Multiplication



Elisabeth Brunet

C = AB

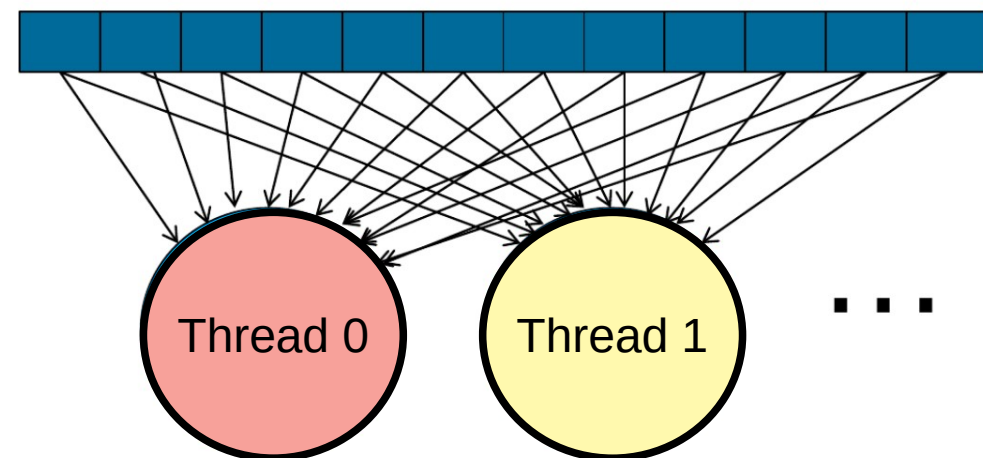
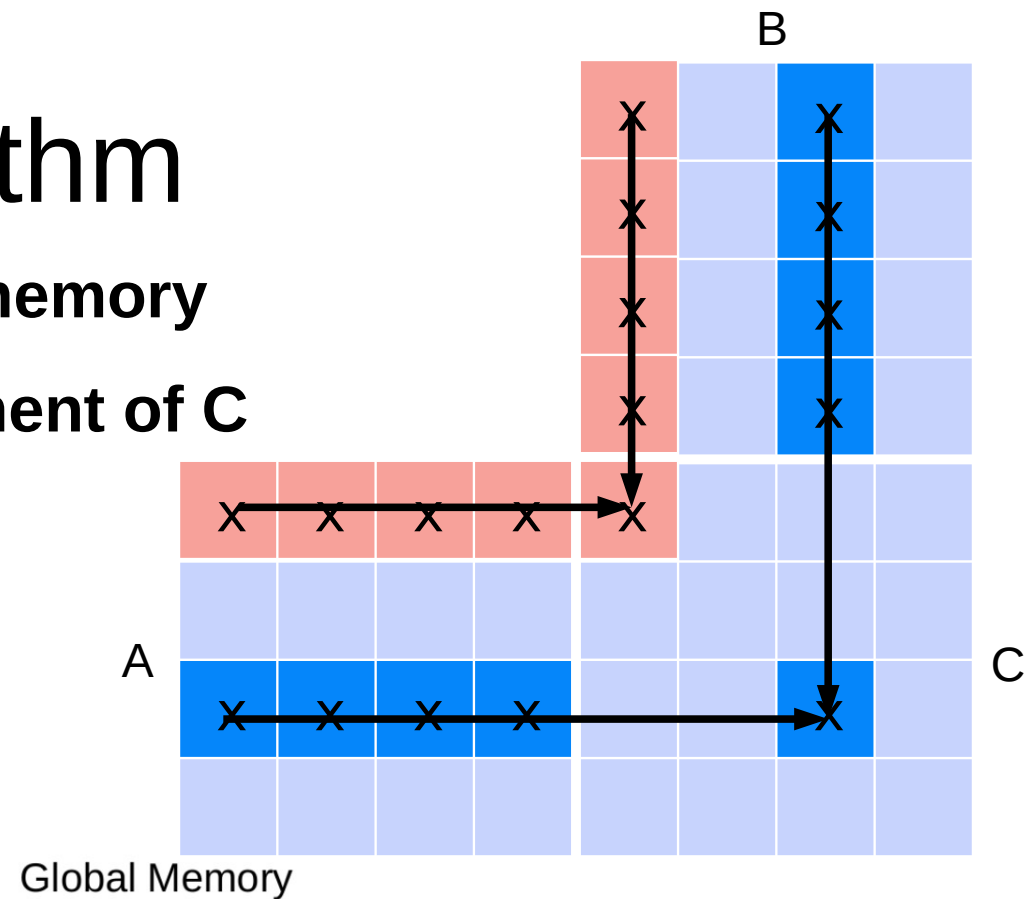
- Given two matrices A and B,



- Such that
$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \cdots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj}$$

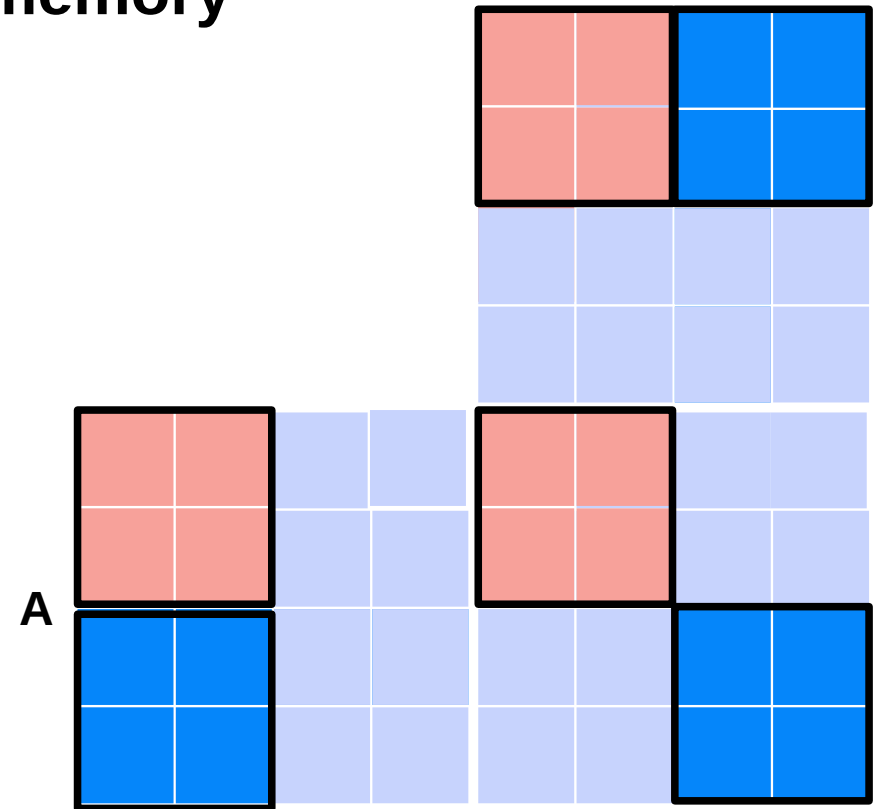
1) Basic algorithm

- Matrices A, B and C in global memory
- Each thread calculates an element of C
- Each thread accesses
 - to a whole line of A
 - and a whole column of B
- Data access non-aligned and scattered
 - Coalescing problem
- Repeated data access



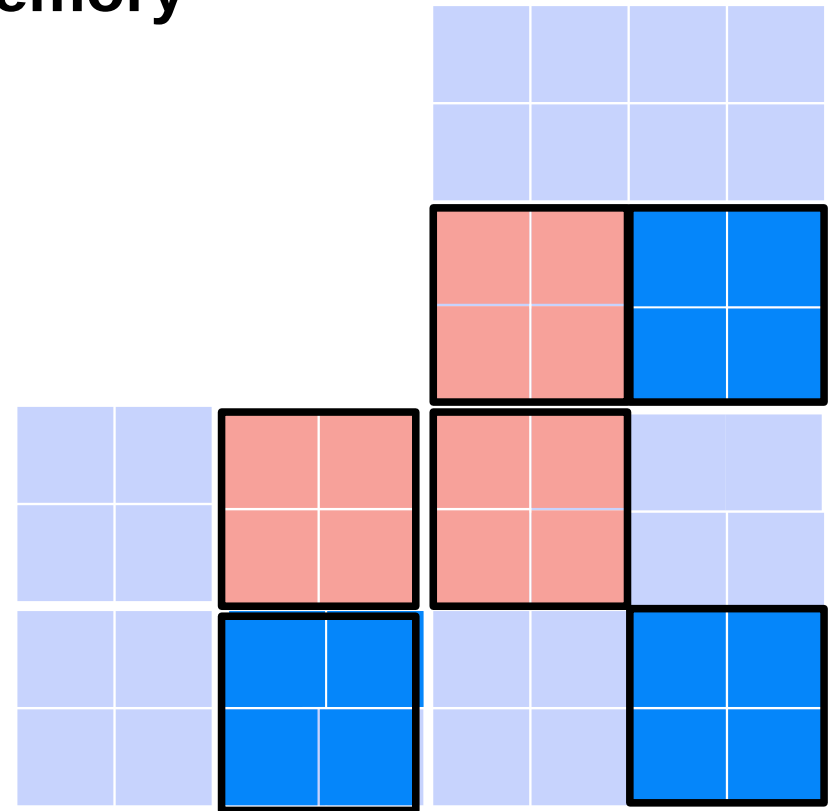
2) Tiled algorithm

- Iterative algorithm
on sub-matrixes multiplication
treated by a block fitting in shared memory



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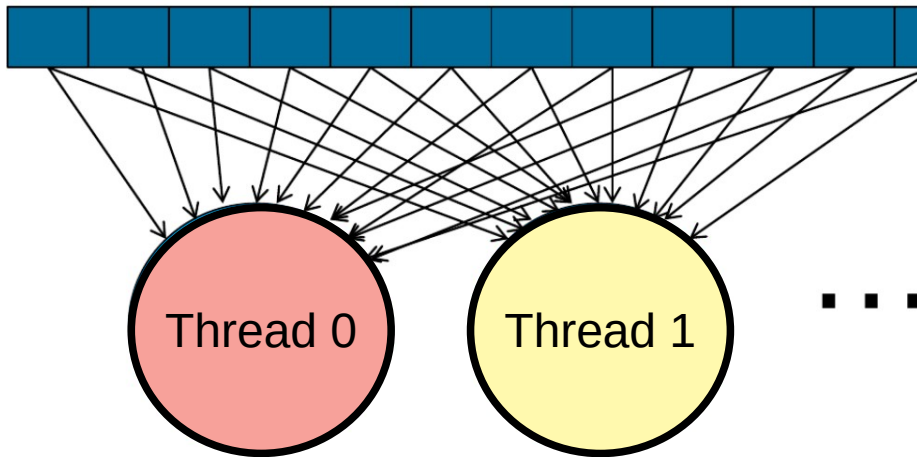
2) Tiled algorithm

- **Iterative algorithm**
on sub-matrixes multiplication
treated by a block fitting in shared memory
- **Iteration in 4 steps :**
 - (a) Cooperative loading of a data in tiles in shared memory
 - (b) Synchronization to ensure that data are loaded
 - (c) Calculation of partial results by threads on loaded data
 - (d) Synchronization before changing the data of the tiles for the next iteration

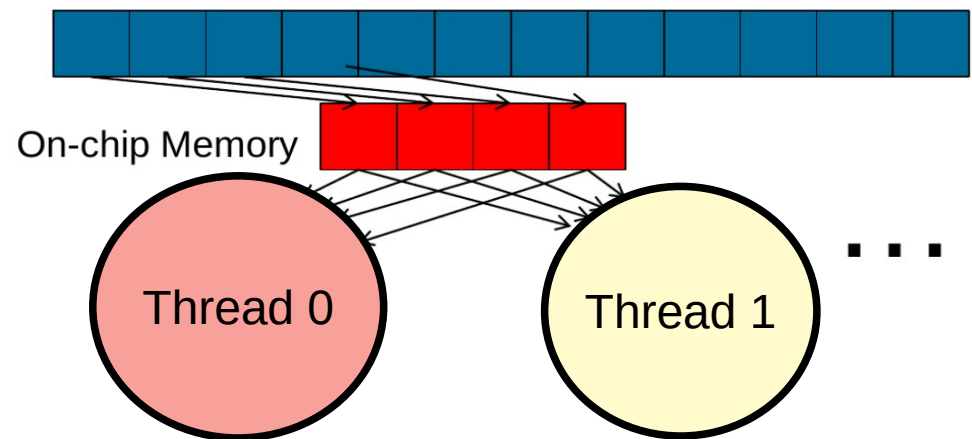
(a) Cooperative data loading _B

- **Objective : change the access pattern**

Global Memory



Global Memory



→ Regular access to global memory
+ Quick access once in shared memory !!!

(a) Cooperative data loading

- **Sub-tiles of $\text{BLOCKSIZE} \times \text{BLOCKSIZE}$ elements**

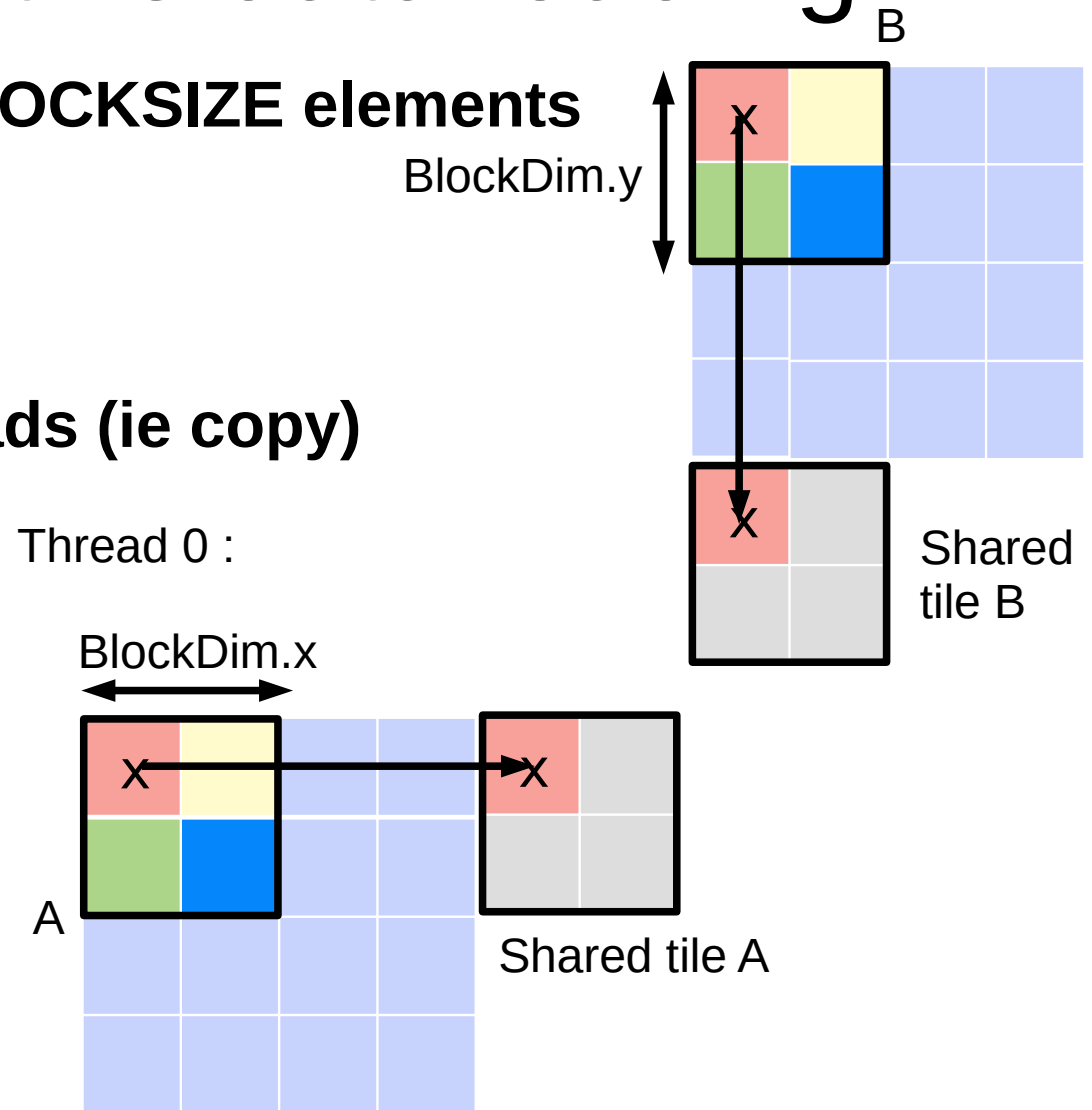
- $\text{BLOCKSIZE} = \text{sqrt}(1024) = 32$

- **Each thread of the block loads (ie copy)**

an element from A

and an element from B

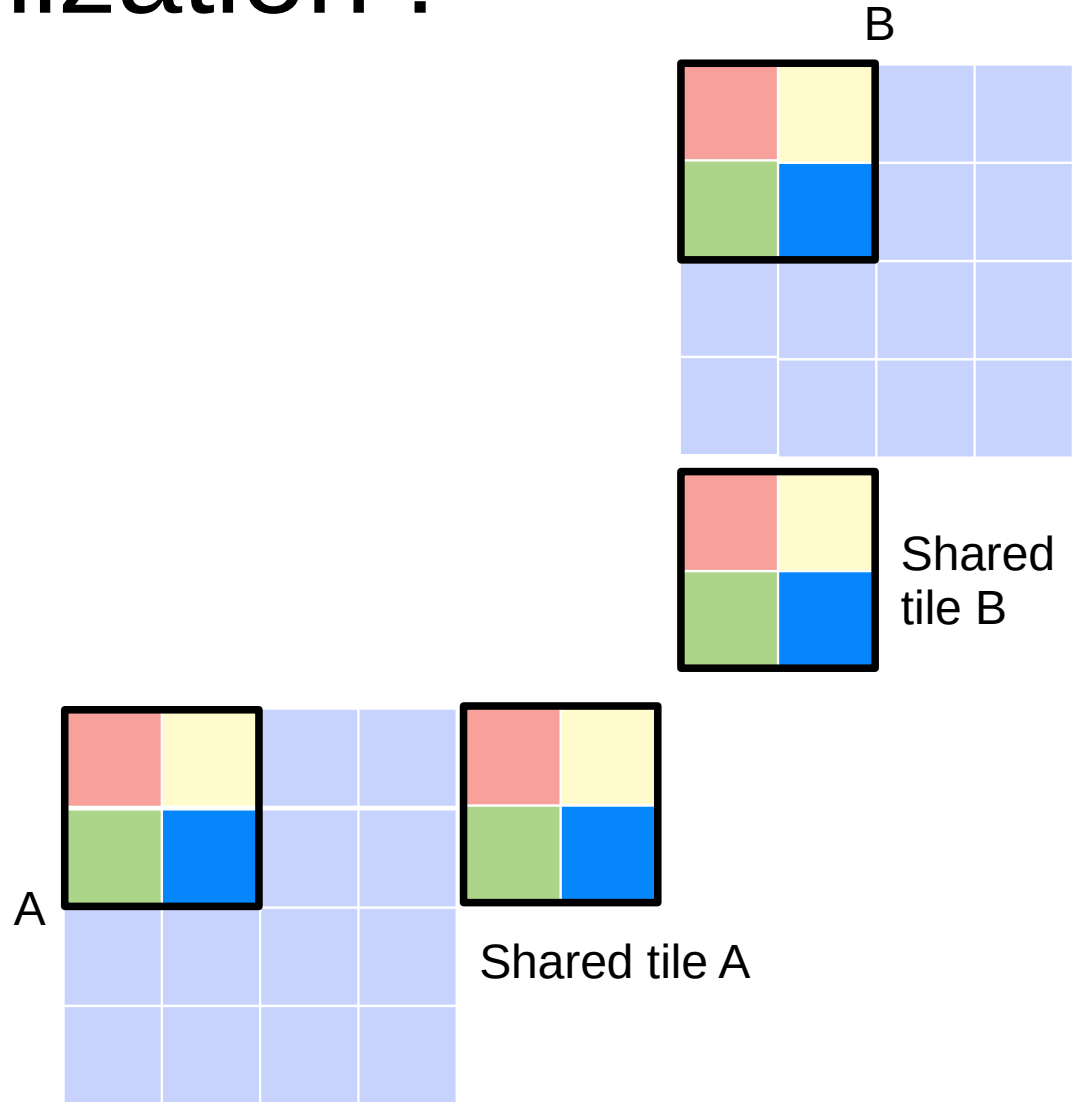
into the shared tiles





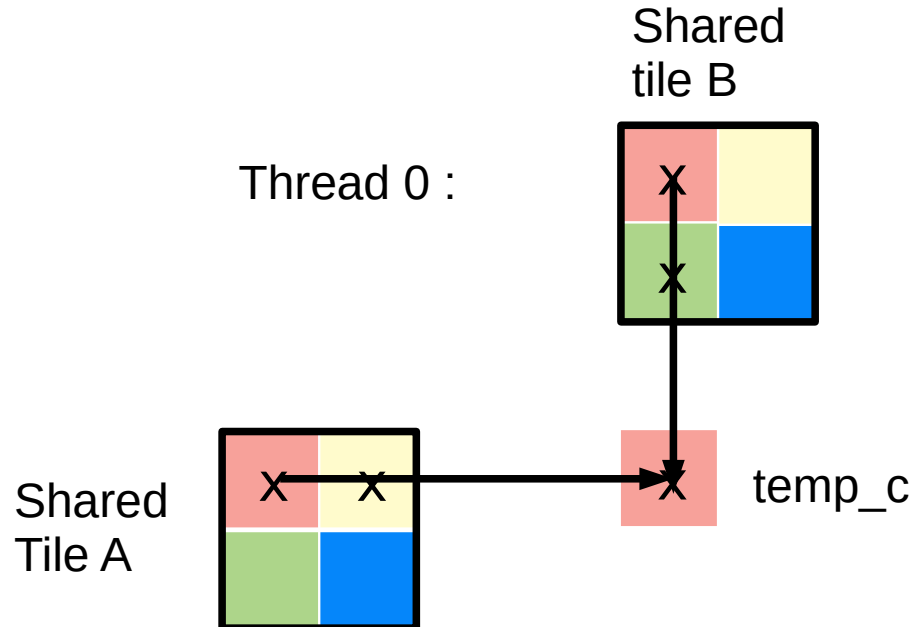
(b) Synchronization !

- Once the barrier passed, the two sub-tiles are complete



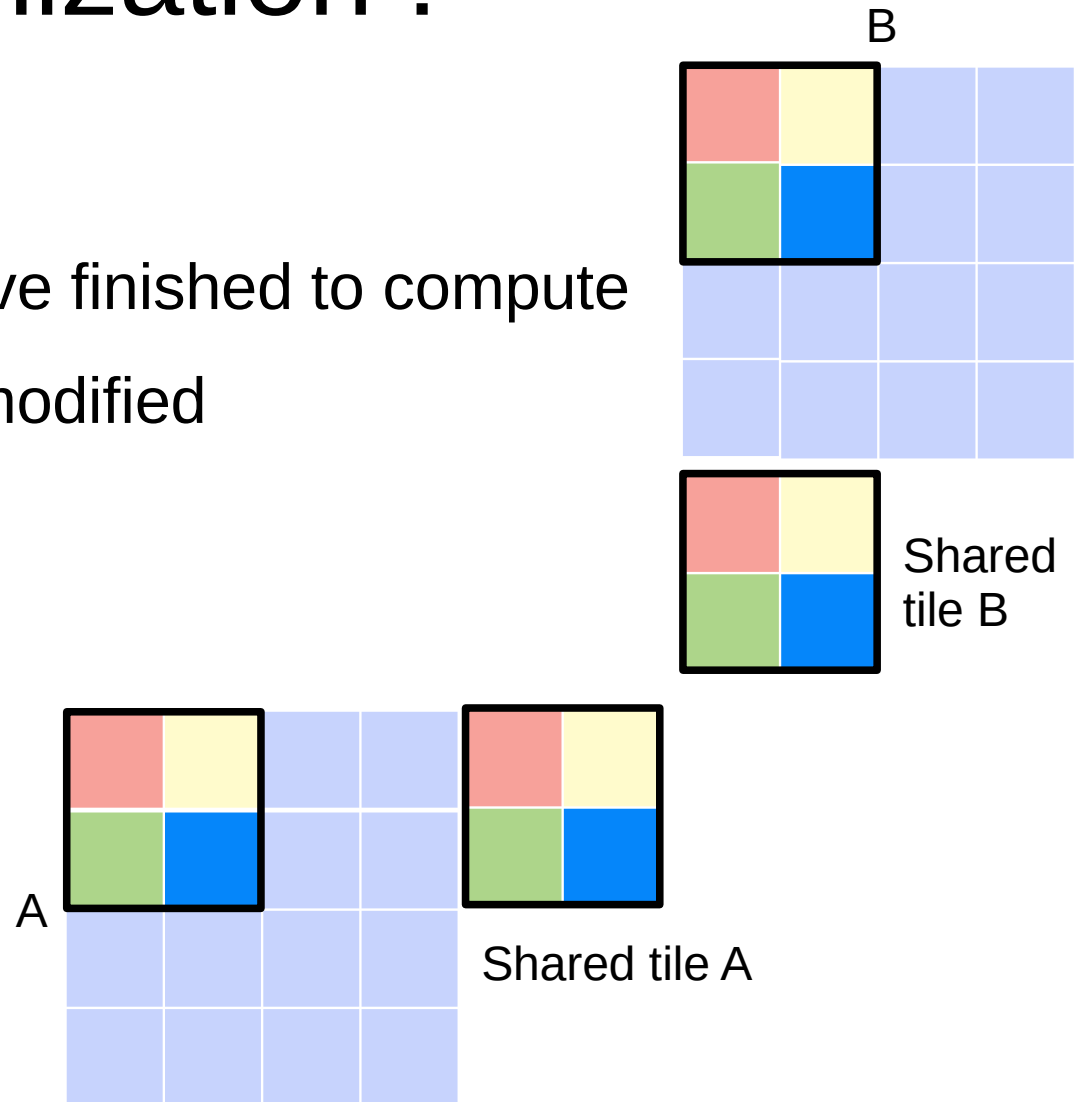
(c) Partial result computation

- Multiplication of matrices on current tiles
- Accumulation in a scalar variable stored in a register



(d) Synchronization !

- Once the barrier passed, all the threads of the block have finished to compute and the two sub-tiles can be modified



Switch to the next tile

(a) Cooperative data loading

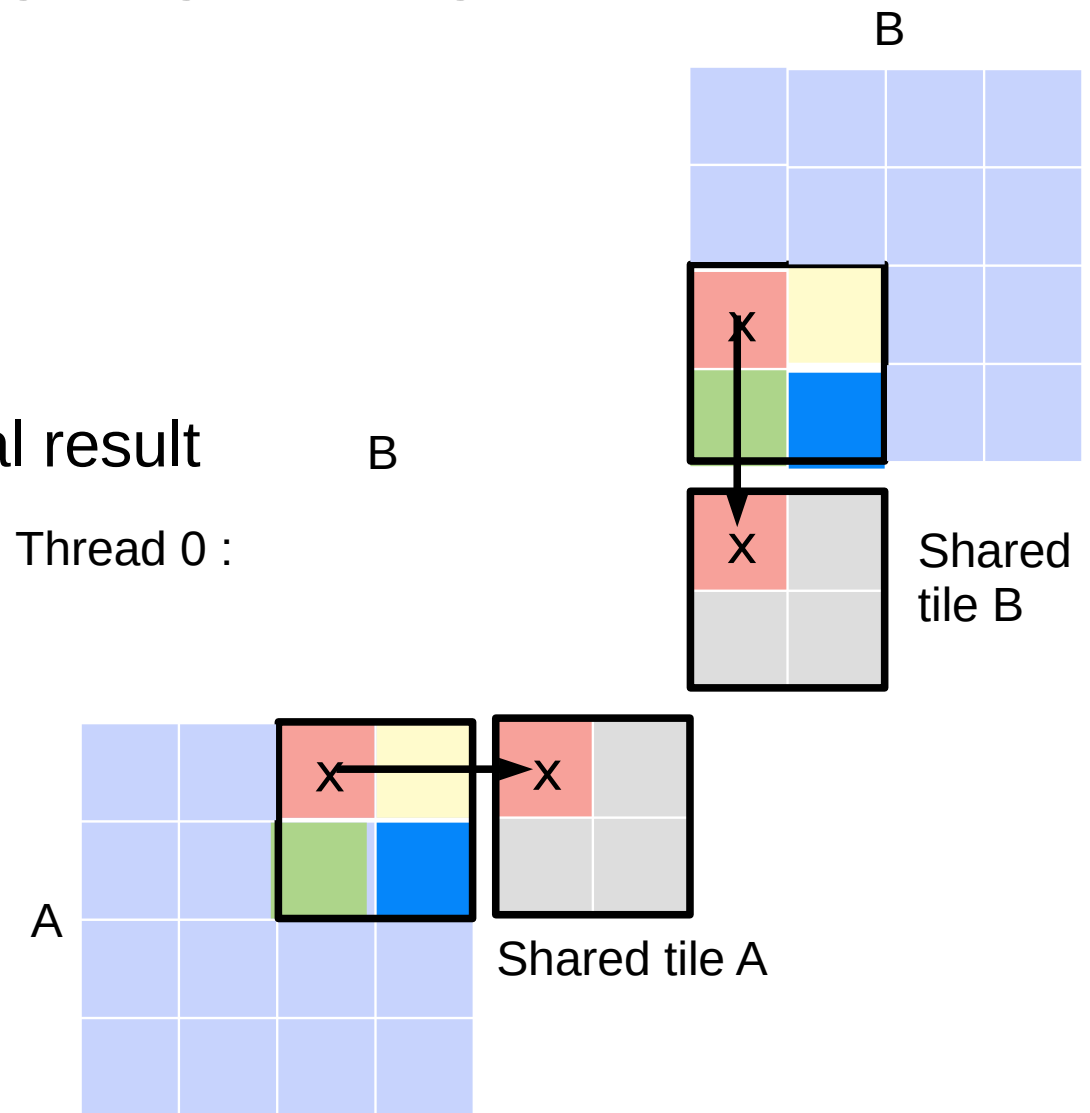
in the **SAME** shared tile

(b) Synchronization

(c) Accumulation of the partial result

in local variable `temp_c`

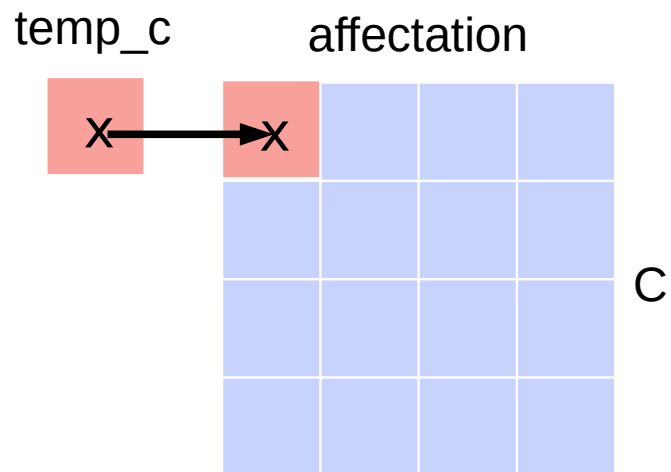
(d) Synchronization



Final result

- Assignment of the result in the C matrix remaining in global memory

Thread 0 :





To go further,

- **Each partial result could be computed by another block**
 - Additional dimension on the grid to identify the tile to be treated
 - Reduction of the partial results :
 - Atomic operation for accumulation: `atomicAdd`
 - Reduction on the GPU thanks to a kernel
 - Reduction on the CPU

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 - Field of research in itself
- **Best algorithms in the cuBLAS library**

Last detail : access to a matrix element

- **Matrix organization**

- = one-dimensional vector column major

- Colum major required by cuBLAS

- **Access to an element in 2 steps**

- 1) Projection of the grid of threads on the matrix

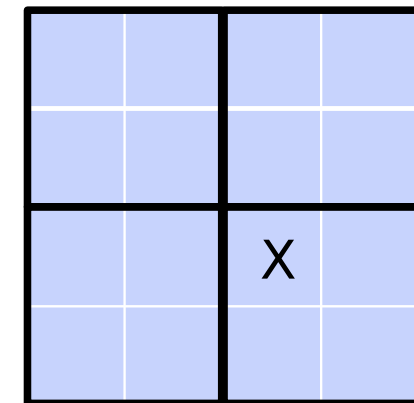
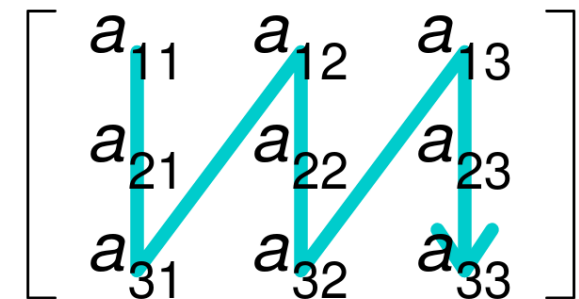
- $\text{Line} = \text{blockIdx.y} * \text{blockDim.y} + \text{threadIdx.y}$
 - $\text{Column} = \text{blockIdx.x} * \text{blockDim.x} + \text{threadIdx.x}$

- 2) Linearization in the data structure

in one column-major dimension

- $A[\text{column} * \text{nbLineOfA} + \text{line}]$
 - Given macro IDX2C : `#define IDX2C(i,j,nb_rows) (((j)*(nb_rows))+i)`

Column-major order





Let's go to practise now !